

Correlations and Semi-Universal Analytic Inversion of the TOV Equation

J. M. Lattimer



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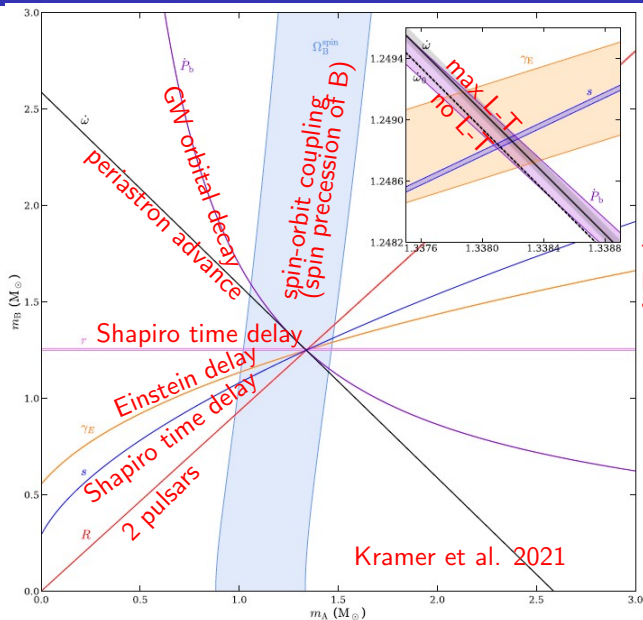
NSF - Neutrinos, Nuclear Astrophysics and Symmetries (PFC - N3AS)

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Recent Collaborators:

Boyang Sun (Stony Brook), Duncan Brown & Soumi De (Syracuse), Christian Drischler, Madappa Prakash & Tianqi Zhao (Ohio), Sophia Han (TDLI), Sanjay Reddy (INT), Achim Schwenk (Darmstadt), Andrew Steiner (Tennessee) & Ingo Tews (LANL)

Pulsar Timing for PSR J0737-3039



$$m_A = 1.338185^{+12}_{-14} M_{\odot}$$

$$m_B = 1.248868^{+13}_{-11} M_{\odot}$$

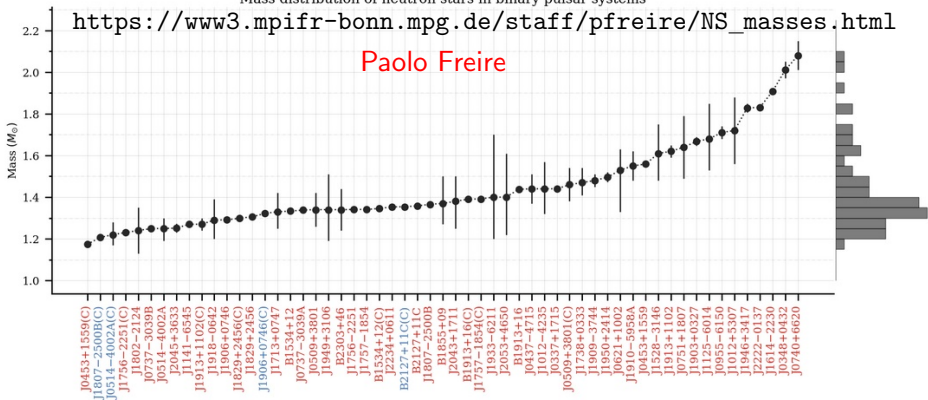
These are the most precisely known masses of any astronomical objects.

Masses of Pulsars in Binaries from Pulsar Timing

Mass distribution of neutron stars in binary pulsar systems

https://www3.mpifr-bonn.mpg.de/staff/pfreire/NS_masses.html

Paolo Freire



Largest: $2.08 \pm 0.07 M_{\odot}$

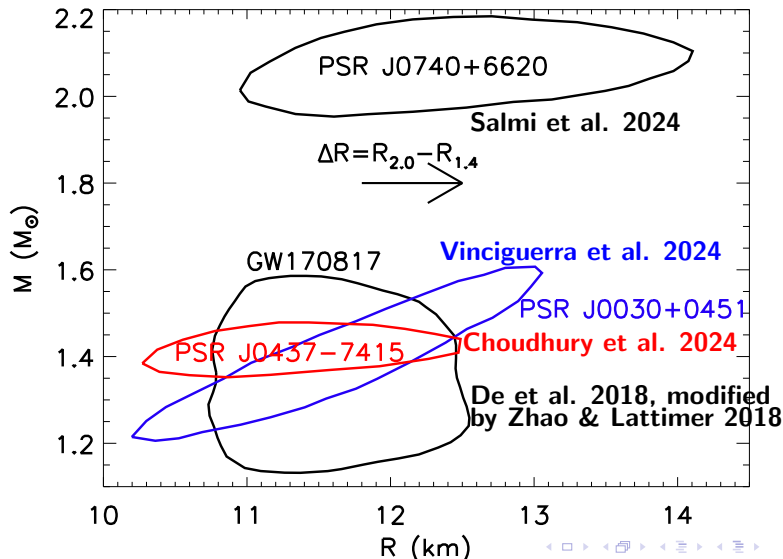
Smallest: $1.174 \pm 0.004 M_{\odot}$

Several other NS masses have been measured by other means, including some estimated to be more than $2M_{\odot}$ (e.g., black widow pulsars) and smaller than $1M_{\odot}$ (HESS J1731-347), but their mass uncertainties are generally large.

How Can a Neutron Star's Radius Be Measured?

- Flux = $\frac{\text{Luminosity}}{4\pi D^2} = \frac{4\pi R^2 \sigma_B T_s^4}{4\pi D^2} = \left(\frac{R}{D}\right)^2 \sigma_B T_s^4$
X-ray observations of quiescent neutron stars in low-mass X-ray binaries measure the flux and surface temperature T_s . Distance D somewhat uncertain; GR effects introduce an M dependence.
- $F_{\text{Edd}} = \frac{GMc}{\kappa D^2}$ X-ray observations of bursting neutron stars in accreting systems measure the Eddington flux F_{Edd} . κ is the poorly-known opacity; GR effects introduce an R dependence.
- X-ray phase-resolved spectroscopy of millisecond pulsars with nonuniform surface emissions (hot spots). NICER: PSR J0030+0451, PSR J0437-4715 (closest and brightest millisecond pulsar) and PSR J0740+6620 (most massive pulsar).
- $R_{1.4} \simeq (11.5 \pm 0.3) \frac{\mathcal{M}}{M_\odot} \left(\frac{\tilde{\Lambda}}{800}\right)^{1/6} \text{ km}$, $\mathcal{M} = \frac{(M_A M_B)^{3/5}}{(M_A + M_B)^{1/5}}$
GW observations of neutron star mergers measure the chirp mass \mathcal{M} and binary tidal deformability $\tilde{\Lambda}$ (GW170817).
- $I_A \propto M_A R_A^2$ Radio observations of extremely relativistic binary pulsars measure masses M_A, M_B and moment of inertia I_A from spin-orbit coupling [PSR J0737-3039 ($P_b = 0.102\text{d}$), PSR J1757-1854 (0.164 d), PSR J1946+2052 (0.078 d)].

Summary of Astrophysical Observations

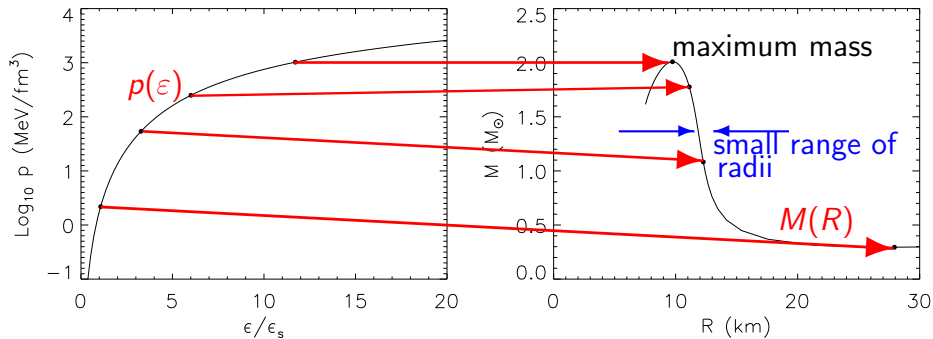


Neutron Star Structure

Tolman-Oppenheimer-Volkov equations

$$\frac{dp}{dr} = -\frac{G}{c^4} \frac{(mc^2 + 4\pi pr^3)(\epsilon + p)}{r(r - 2Gm/c^2)}$$

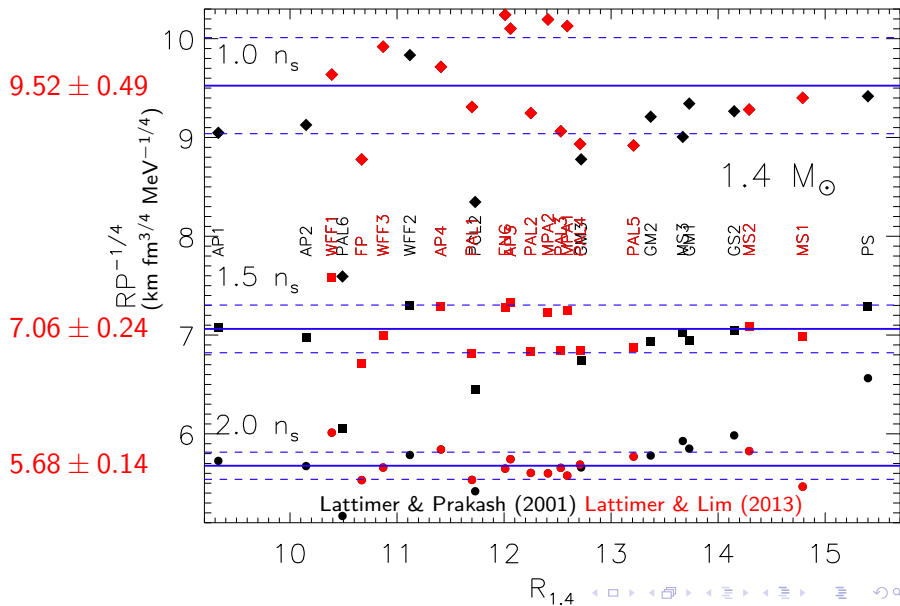
$$\frac{dm}{dr} = 4\pi \frac{\epsilon}{c^2} r^2$$



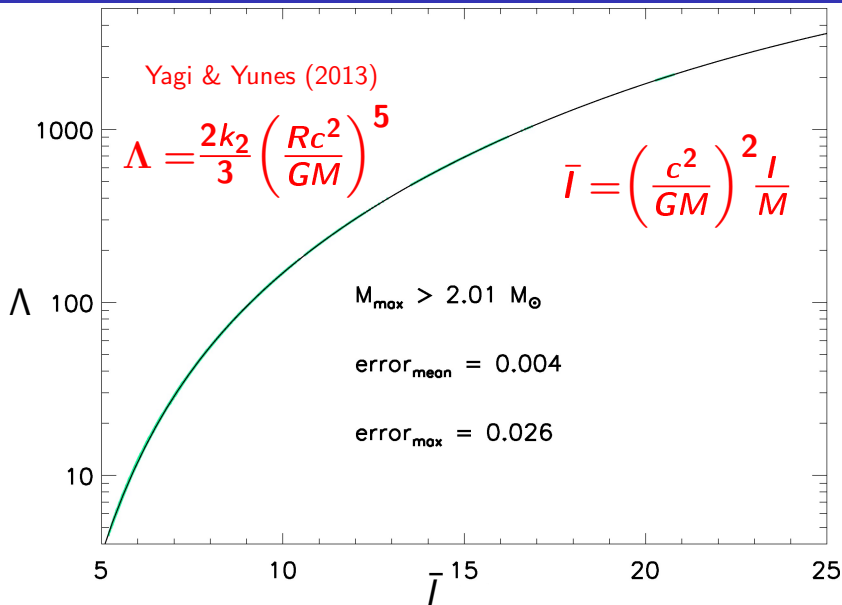
Equation of State

Observations

The Radius – Pressure Correlation



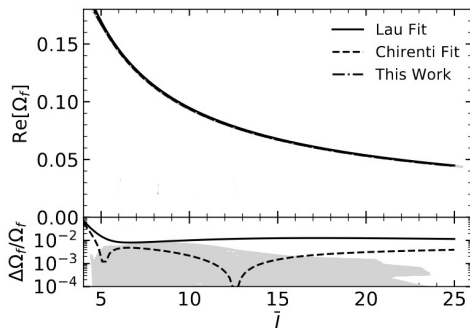
The I-Love Relation



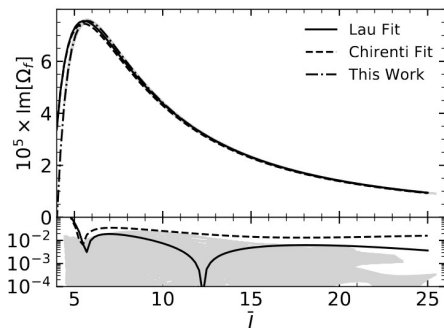
F-Mode Properties - Moment of Inertia

$$\Omega_f = \frac{GM\omega_f}{c^3}$$

Zhao & Lattimer 2022

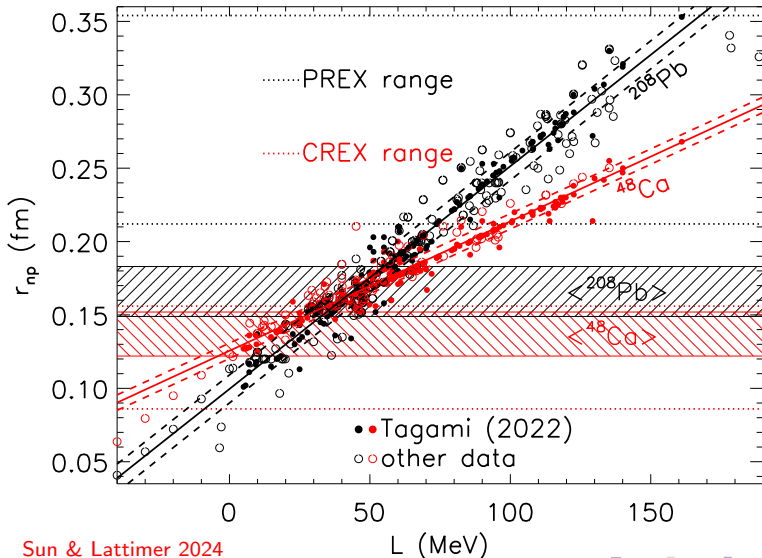


frequency



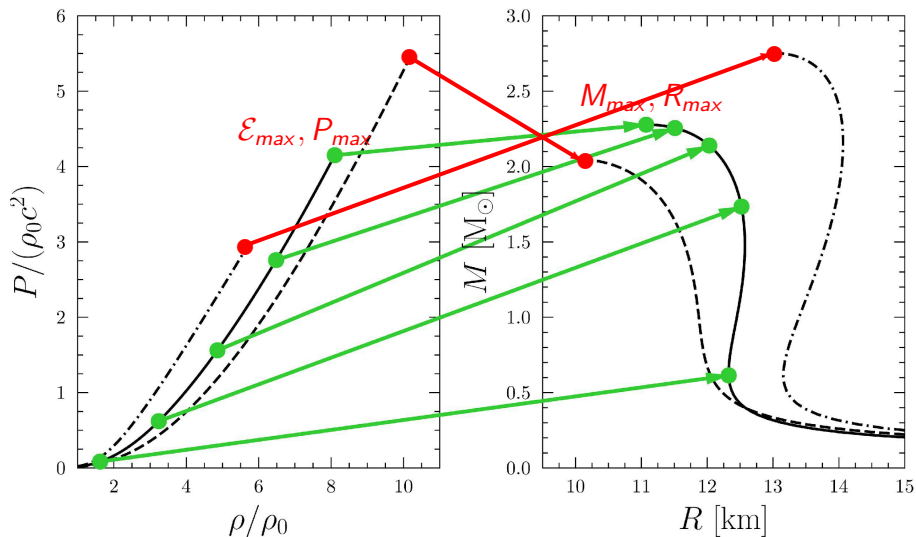
damping time

Neutron Skin Thickness - L

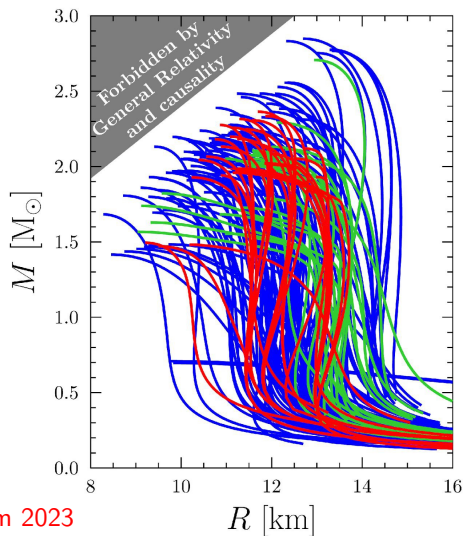
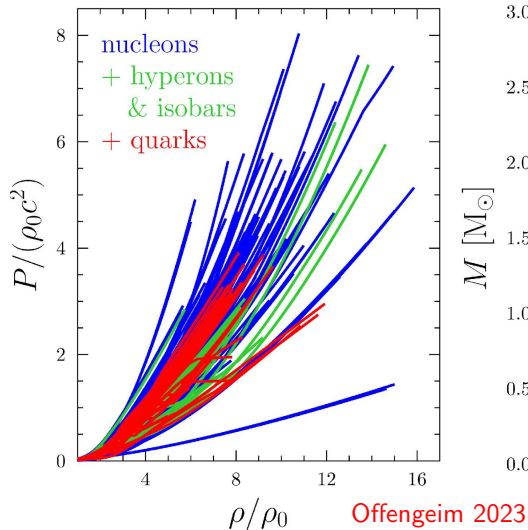


Sun & Lattimer 2024

Maximum Mass As a Unique Scaling Point



Varying the EOS



M_{\max} , R_{\max} , \mathcal{E}_{\max} , P_{\max} Correlations

- Ofengeim(2020) fitted \mathcal{E}_{\max} and P_{\max} with the functions

$$\mathcal{E}_{\max}, P_{\max} \simeq \left[\frac{a_{\mathcal{E},P}}{R_{\max} \cos \phi_{\mathcal{E},P} + (GM_{\max}/c^2) \sin \phi_{\mathcal{E},P} + d_{\mathcal{E},P}} \right]^{S_{\mathcal{E},P}}$$

with accuracies of about 3% and 8%, respectively.

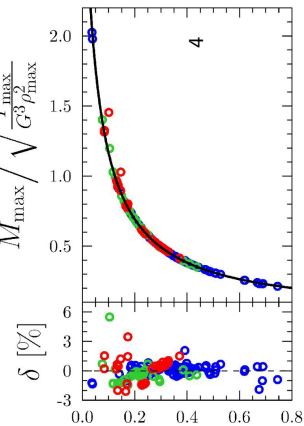
- Cai, Li and Zhang (2023) found a perturbative solution of the TOV equations in the parameter $x = P_c/\mathcal{E}_c$:

$$R \simeq \sqrt{\frac{3c^2}{2\pi G\mathcal{E}_c}} \left[\frac{x}{1+4x+3x^2} \right]^{1/2},$$
$$M \simeq \sqrt{\frac{54c^6}{\pi G^3\mathcal{E}_c}} \left[\frac{x}{1+4x+3x^2} \right]^{3/2}.$$

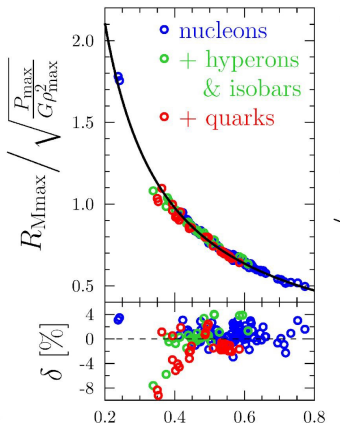
At M_{\max} , accuracies are 7% and 8%; at $1.4M_{\odot}$, they are 2% and 6%.

- Ofengeim et al. (2023) suggested fits for M_{\max} , R_{\max} :

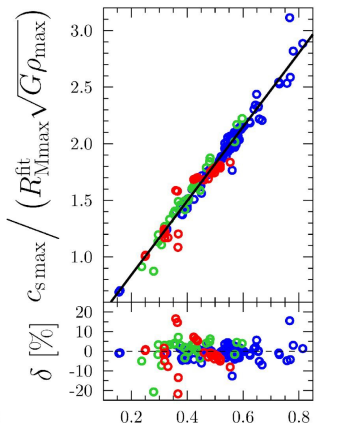
$$M_{\max} \simeq \frac{a_M \mathcal{E}_{\max}^{-1/2} x^{3/2}}{b_M + c_M x^{p_M} \mathcal{E}_{\max}^{q_M}}, \quad R_{\max} \simeq \frac{a_R \mathcal{E}_{\max}^{-1/2} x^{1/2}}{b_R + c_R x^{p_R} \mathcal{E}_{\max}^{q_R}}$$



$$\left(\frac{P_{\max}}{\rho_0 c^2}\right)^{1.41} \left(\frac{\rho_{\max}}{\rho_0}\right)^{-1.39}$$



$$\left(\frac{P_{\max}}{\rho_0 c^2}\right)^{0.52} \left(\frac{\rho_{\max}}{\rho_0}\right)^{-0.59}$$



$$\left(\frac{P_{\max}}{\rho_0 c^2}\right)^{0.76} \left(\frac{\rho_{\max}}{\rho_0}\right)^{-0.78}$$

$M_{\max}, R_{\max}, \mathcal{E}_{\max}, P_{\max}$ Correlation

Ofengeim et al's finding suggest the power-law correlations

$$\mathcal{E}_{c,\max} = (1.809 \pm 0.36) \left(\frac{R_{\max}}{10\text{km}} \right)^{-1.98} \left(\frac{M_{\max}}{M_{\odot}} \right)^{-0.171} \text{ GeV fm}^{-3},$$

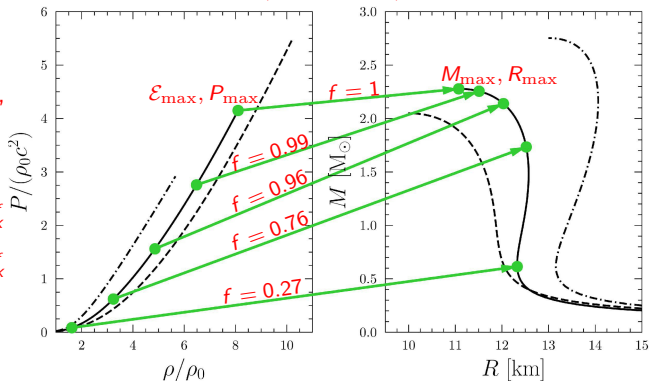
$$P_{c,\max} = (118.5 \pm 6.2) \left(\frac{R_{\max}}{10\text{km}} \right)^{-5.24} \left(\frac{M_{\max}}{M_{\odot}} \right)^{2.73} \text{ MeV fm}^{-3},$$

which are accurate to about 5% in fitting $\mathcal{E}_{c,\max}$ and $P_{c,\max}$.

Points along $M - R$ curves, at $M = fM_{\max}$, have similarly accurate correlations:

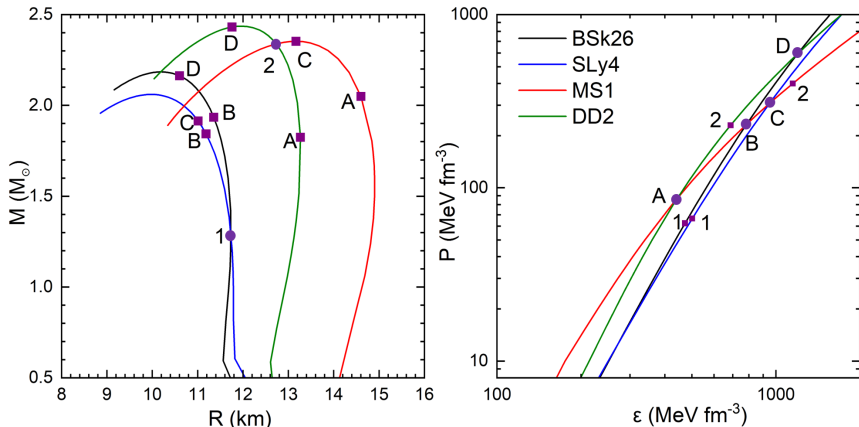
$$\mathcal{E}_{c,f} = a_{\mathcal{E},f} R_{fM_{\max}}^{b_{\mathcal{E},f}} M_{\max}^{c_{\mathcal{E},f}}$$

$$P_{c,f} = a_{P,f} R_{fM_{\max}}^{b_{P,f}} M_{\max}^{c_{P,f}}$$



(M, R) Is Not Equivalent To (\mathcal{E}_c, P_c)

While the maximum mass point (M_{max}, R_{max}) predicts $(\mathcal{E}_{c,max}, P_{c,max})$ to about 5%, and similarly for a given fractional maximum mass fM_{max} , the inversion is not unique. Two different equations of state predicting the same (M, R) (numbers in figure) arrive at those values from integration via different paths in (\mathcal{E}, P) space. Similarly, two equations of state with identical values of (\mathcal{E}_c, P_c) (letters) do not have the same (M, R) values.



Correlations at $M = fM_{\max}$

Thus, more information than (M, R) needed. We find precision is greatly improved using a 2nd radius from a grid of fractional M_{\max} points, e.g., $f \in [1, 0.95, 0.9, 0.85, 4/5, 3/4, 2/3, 0.6, 0.5, 0.4, 1/3]$.

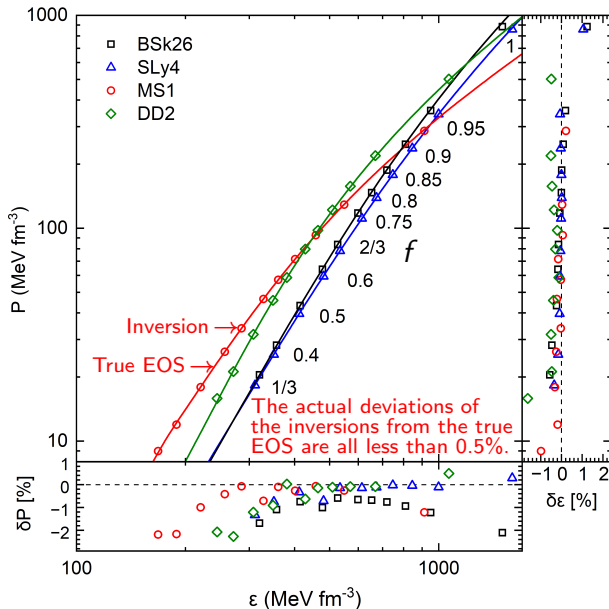
$$\mathcal{E}_f = a_{\mathcal{E},f} \left(\frac{R_{f_1}}{10\text{km}} \right)^{b_{\mathcal{E},f_1}} \left(\frac{R_{f_2}}{10\text{km}} \right)^{c_{\mathcal{E},f_2}} \left(\frac{M_{\max}}{M_{\odot}} \right)^{d_{\mathcal{E},f}},$$

$$P_f = a_{P,f} \left(\frac{R_{f_1}}{10\text{km}} \right)^{b_{P,f_1}} \left(\frac{R_{f_2}}{10\text{km}} \right)^{c_{P,f_2}} \left(\frac{M_{\max}}{M_{\odot}} \right)^{d_{P,f}},$$

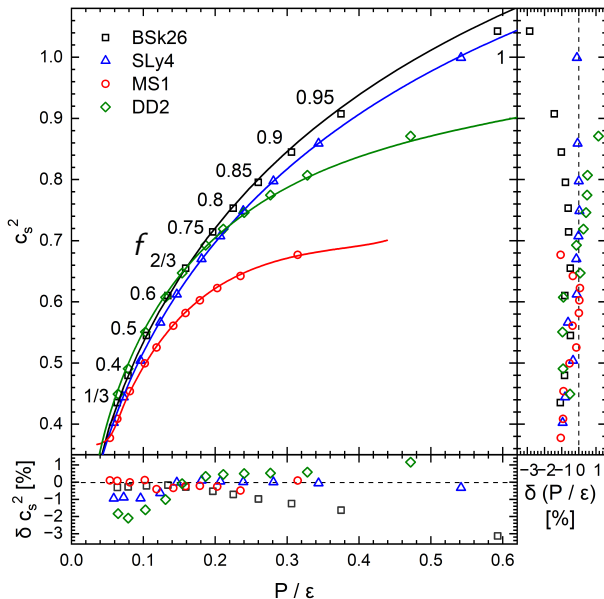
$f = M/M_{\max}$	f_1	f_2	$\Delta(\ln \mathcal{E}_f)$	f_1	f_2	$\Delta(\ln P_f)$
1	0.95	0.9	0.00469	1	3/5	0.0123
0.95	0.95	4/5	0.00275	0.95	3/5	0.00722
0.90	0.95	2/3	0.00227	0.95	2/5	0.00517
0.85	0.95	1/2	0.00237	0.9	2/5	0.00491
4/5	0.9	1/2	0.00230	0.85	2/5	0.00463
3/4	0.85	1/2	0.00239	4/5	2/5	0.00539
2/3	3/4	1/2	0.00277	2/3	2/5	0.00513
3/5	3/4	2/5	0.00339	2/3	1/3	0.0172
1/2	2/3	1/3	0.00477	1/2	2/5	0.00996
2/5	1/2	1/3	0.00706	1/2	1/3	0.0187
1/3	1/2	1/3	0.0122	2/5	1/3	0.0259

greatly reduced
uncertainties!

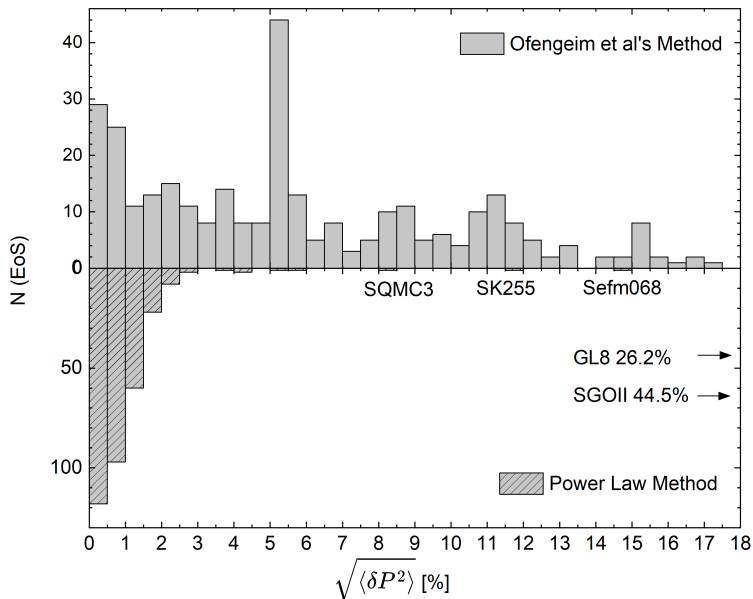
Testing the Inversion



Testing the Inversion for $c_s^2 - P/\epsilon$



Comparing Inversions



Inversion of $M - R$ Data

Instead of inverting an $M - R$ curve one may wish to infer the EOS from $M - R$ data. Traditional Bayesian inversions begin with $M - R$ priors generated by sampling millions of trials using a specific EOS parameterization with uniform distributions of parameters within selected ranges.

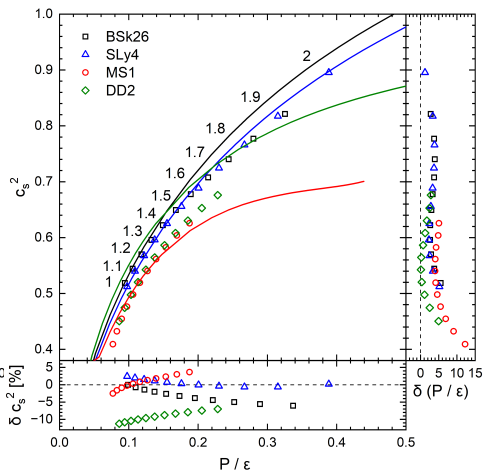
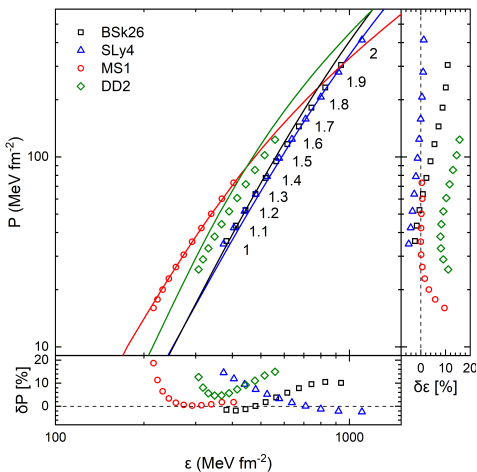
One problem with our approach is that M_{max} and R_{max} are not known. One can form analytical correlations between (M, R) and (\mathcal{E}_c, P_c) , but these have only moderate accuracy since this inversion is not unique. More information than the $M - R$ point itself is necessary to improve the inversion.

One possibility is to include the inverse slope dR/dM at the (M, R) point. Generally, one can determine a correlation between a quantity $G \in [\mathcal{E}_c, P_c, \text{etc.}]$ and $(M, R, dR/dM)$ in the form

$$\ln G = \ln a_G + b_G \ln M + c_G \ln R + d_G (dR/dM).$$

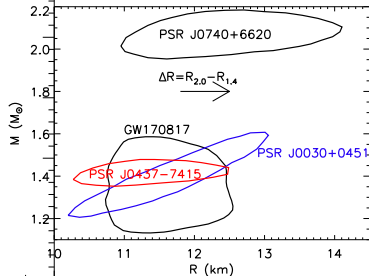
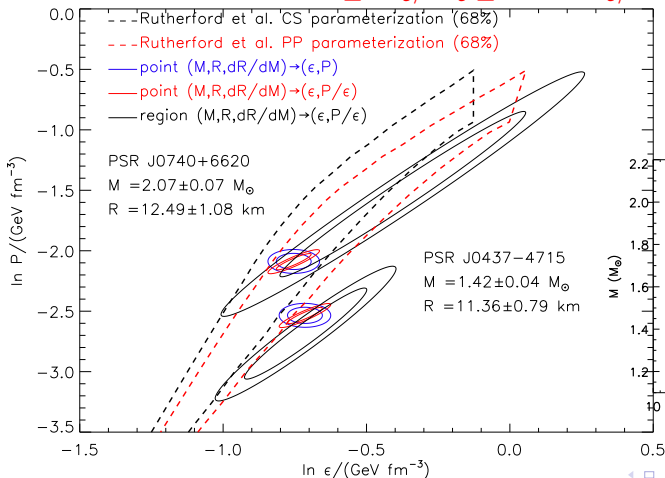
Including dR/dM information improves correlations by factors of about 2. It is also found that inferred values of \mathcal{E}_c and P_c are highly correlated; fits to P_c/\mathcal{E}_c have much smaller uncertainty than fits to \mathcal{E}_c or P_c .

Testing the $M - R$ Inversion



Comparison to Traditional Bayesian Inference

From two $M - R$ regions obtained from observations select random pairs of points and determine dR/dM . Then, using the above correlation formulae, infer two $\mathcal{E}_c - P_c$ uncertainty regions (after rejecting pairs that violate the conditions $0 \leq dP_c/d\mathcal{E}_c \leq 1$ and $dP_c/dM > 0$).



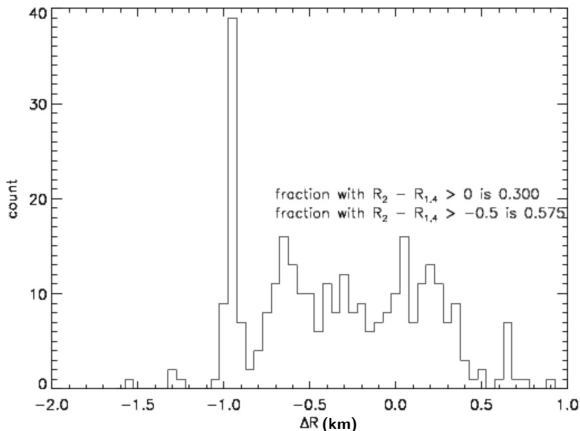
Importance of $\Delta R = R_{2.0} - R_{1.4}$

• J0437-4715:
 $R = 11.36^{+0.95}_{-0.63}$ km

• J0740+6620:
 $R = 12.49^{+1.28}_{-0.88}$ km

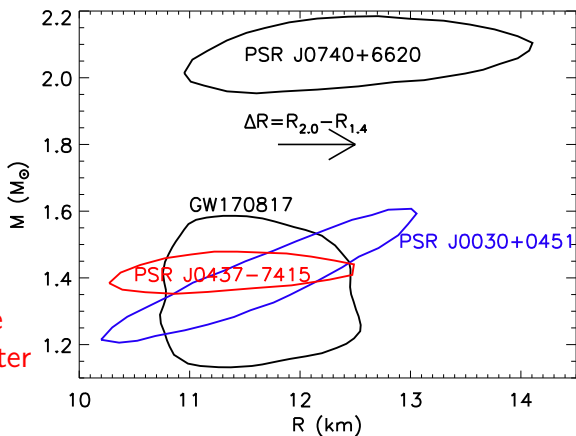
$\Delta R = +1.13^{+1.59}_{-1.08}$ km

313 Skyrme + RMF forces with $M_{max} \geq 2.0M_{\odot}$



Applications

- Analytic inversion of TOV equations with arbitrarily high accuracies (depends on number of R_f values).
- Existing techniques use parameterized EOS models in probabilistic (Bayesian) approaches having unquantified systematic uncertainties stemming from the model and parameter choices (prior distributions).



- Since M and R can't uniquely determine \mathcal{E}_c and P_c , we use the value of (dR/dM) to improve accuracies.
- Correlations of c_s with M , R and dR/dM can be used to further improve the fidelity of inversions and also for interpolating within the $\mathcal{E}_f - P_f$ grid. They could also allow probing the composition of the neutron star interior (phase transitions, etc.).
- Correlations of $\tilde{\Lambda}$, \bar{I} and BE/M with M and R also exist and aren't sensitive to dR/dM .
- This inversion technique might have wider applicability to other physics or engineering problems.